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Determination of Coefficients of Capacitance of Regions Bounded by Collinear Slits and of Related Regions

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DETERMINATION OF COEFFICIENTS OF CAPACITANCE OF REGIONS

BOUNDED BY COLLINEAR SLITS AND OF RELATED REGIONS

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Abstract

A number of formulas are derived for the coefficients of capacitance of a domain which consists of the entire plane minus any finite number of col-linear slits. It is shown that any of a broad class of domains possessing a certain symmetry property is conformally equivalent to such a 'slit-domain', and that the problem of determining the conformal correspondence is essential-ly one of mapping simply-connected domains rather than multiply-connected ones. As an illustration, the coefficients of capacitance of a 'bi-filar shielded cable' are computed.

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1. Introduction

In the study of electrostatic field problems the principal objective usually is to determine the potential and its gradient (the field strength) throughout a given domain bounded by a system of conductors. Frequently, however, it is necessary only to determine certain constants of capacitance. In this paper we consider the latter problem for a certain class of plane domains.

Let D be a domain consisting of the entire x-y plane with any finite number of slits along a single line. Several formulas for the coefficients of capacitance of such a domain are derived, two of which appear to be well suited for numerical computations. One of these formulas is based on the explicit representation of the potential as the real part of an analytic function [1],[2] while the other formula has the feature of requiring a knowledge of the potential only on the line containing the boundary components of D; it does not involve any derivatives of the potential. A convenient method for determining the field along the line containing the boundary components has been given by the author in a previous paper.[2]

Since the coefficients of capacitance of a domain are invariant under conformal mapping, the formulas which are derived may be employed to compute the coefficients of any domain which can be conformally mapped upon a domain D of the type described above. This procedure can be applied to a certain class of domains which are of practical interest. In these cases the mapping problem involves essentially only simply-connected domains rather than multiply-connected domains. One particular case of interest, the 'bi-filar shielded cable' is considered in some detail, and as an illustration of the procedure, the coefficients of capacitance are evaluated numerically for one such domain.

2. Regions Bounded by Collinear Slits

We consider here the problem of determining effectively the so-called coefficients of capacitance of a domain D consisting of the extended (x,y)-plane with a finite number, m, of collinear slits, cut along what may be assumed to be the x-axis.

We recall the definition of these coefficients:

$$(2.1) \qquad p_{ik} = - \oint_{C_k} \frac{\partial u_i}{\partial n} \, ds, \quad (i, \, k = 1, 2, \cdots, m),$$

where u_i, the harmonic measure of the i-th boundary component, is the harmonic function whose boundary values are unity on the i-th component and zero on all other components (the existence and uniqueness of this harmonic function is well known from the theory of the Dirichlet problem); C_k is any curve, described in the positive sense, surrounding only the k-th component; and $\frac{\partial}{\partial n}$ indicates differentiation in the direction of the outward normal. As follows immediately from the Cauchy-Riemann equations, the p_{ik} may be defined alternatively as the increment in the harmonic function v_i conjugate to u_i which results when C_k is described once in the negative sense.

We also recall several important properties of these coefficients of capacitance:

$$(2.2a) \qquad p_{ik} = p_{ki} \, ;$$

$$(2.2b) \qquad \sum_{k=1}^{m} p_{ik} = 0, \qquad i = 1, 2, \cdots, m \, ;$$

$$(2.2c) \qquad p_{ii} > 0 \, ;$$

$$(2.2d) \qquad p_{ik} < 0, \qquad i \neq k.$$

The p_{ik} are, of course, conformal invariants. Hence we may assume that D consists of the entire plane minus a finite number of slits lying on the x-axis, one of which extends to infinity in both directions (see Fig. 1); this configuration can always be realized by a suitable inversion. It will be seen

that this assumption eliminates the possibility of any convergence difficulties. For brevity such domains will be called slit-domains. We number the finite slits 1, 2, $\cdots$, m-1 from left to right; and the infinite slit is the m-th.
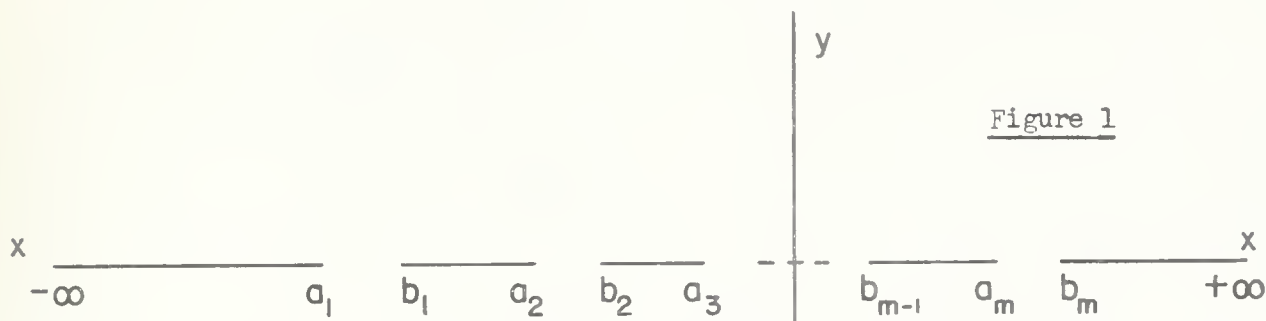

Figure 1

We proceed to derive various formulas for the quantities p_{ik} which may prove useful for numerical computations. First we shall employ the definition (2.1); later we shall derive a formula based on the alternative definition given following (2.1).

Taking into account (2,2a) and (2.2b) we see that it suffices to determine the p_{ik} with i < m, k < m. Let $f_i(x) = u_i(x,0)$, so that, in particular, $f_i(x) = 0$ for $x \leq a_1$, $x \geq b_m$. By the Poisson formula we have, for any point off the x-axis:

$$(2.3) \qquad u_i(x,y) = \frac{|y|}{\pi} \int_{a_1}^{b_m} \frac{f_i(\xi)d\xi}{(\xi-x)^2+y^2} .$$

We take as the curve C_k a rectangle with vertical sides passing through the gaps (a_k, b_k) and (a_{k+1}, b_{k+1}). It is easily found from (2.3), by differentiating under the integral sign, that for any value of x:

$$(2.4) \qquad \left|\frac{\partial u_i}{\partial x}\right| \leq \frac{2A^2}{\pi y^3} , \qquad \left|\frac{\partial u_i}{\partial y}\right| \leq \frac{2A}{\pi y^2} , \qquad A = \max(|a_1|, |b_m|)$$

(one uses, of course, the fact that $|f_i(\xi)| \leq 1$). Hence as the horizontal sides recede to infinity the contribution to the integral (2.1) from these sides vanishes, and therefore (2.1) may be written as follows:

$$(2.5) \qquad p_{ik} = I_{i,k} - I_{i,k+1} ,$$

where

(2.6) $$I_{i,j} = \int_{-\infty}^{\infty} \frac{\partial u_i}{\partial x} \, dy, \quad a_j < x < b_j$$

(of course $p_{im} = I_{i,m} - I_{i,1}$).

We wish to rewrite $I_{i,j}$ in such a form as to involve only the values of u_i on the x-axis, i.e., the values $f_i(x)$. If one expresses $\frac{\partial u_i}{\partial x}$ by differentiating (2.3), inserts this expression into (2.6), and interchanges the order of integration, one obtains the following expression for $I_{i,j}$:

(2.7) $$I_{i,j} = \frac{2}{\pi} P \int_{a_1}^{b_m} \frac{f_i(\xi) d\xi}{\xi - x}, \quad a_j < x < b_j.$$

Here the symbol P denotes the Cauchy principal value of the integral.

A second expression for $I_{i,j}$ is obtained by the following artifice: Since the right side of (2.6) gives the same value for any choice of x in the j-th gap, we integrate both sides of (2.6) over this gap. Then we obtain

$$(b_j - a_j) I_{i,j} = \int_{a_j}^{b_j} \int_{-\infty}^{\infty} \frac{\partial u_i}{\partial x} \, dy dx.$$

Interchanging the order of integration [this is easily justified with the aid of the first inequality in (2.4)] we obtain

(2.8) $$(b_j - a_j) I_{i,j} = \int_{-\infty}^{\infty} \int_{a_j}^{b_j} \frac{\partial u_i}{\partial x} \, dx dy = \int_{-\infty}^{\infty} \left\{ u(b_j, y) - u(a_j, y) \right\} dy =$$

$$= \frac{1}{\pi} \int_{-\infty}^{\infty} |y| \left\{ \int_{a_1}^{b_m} f_i(\xi) \left[\frac{1}{(\xi - b_j)^2 + y^2} - \frac{1}{(\xi - a_j)^2 + y^2} \right] d\xi \right\} dy.$$

Now we interchange the order of integration once more, and obtain the following expression for $I_{i,j}$:

(2.9) $$I_{i,j} = \frac{2}{\pi (b_j - a_j)} \int_{a_1}^{b_m} f_i(\xi) \ln \left| \frac{\xi - a_j}{\xi - b_j} \right| d\xi.$$

A third expression for $I_{i,j}$ is obtained as follows. Since $f_i(\xi)$ is con-

tinuous and $f_i'(\xi)$ and $\ln\left|\dfrac{\xi-a_j}{\xi-b_j}\right|$ are absolutely integrable, an integration by parts enables us to rewrite (2.9) in the form:

$$(2.10) \qquad I_{i,j} = \frac{-2}{\pi(b_j-a_j)} \int_{a_1}^{b_m} f_1'(\xi)\left[(\xi-a_j)\ln|\xi-a_j|-(\xi-b_j)\ln|\xi-b_j|\right]d\xi;$$

the integrated term vanishes since $f_i(a_1) = f_i(b_m) = 0$.

Equations (2.7), (2.9), (2.10), together with (2.5), give three formulas for the coefficients p_{ik} which employ only the values of u_i on the x-axis. These equations were all derived using the definition (2.1) of p_{ik}. A fourth formula is obtained by using the alternative definition, as follows. It is shown in [1], § 91 that the analytic function $w_i(z) = u_i+i\,v_i$ must satisfy the condition

$$(2.11) \qquad w_i'(z) = \frac{P_i(z)}{\sqrt{-\displaystyle\prod_{j=1}^{m}(z-a_j)(z-b_j)}}$$

where $P_i(z)$ is a polynomial, of degree not exceeding m-2, with m-1 real co-efficients which are uniquely determined by the conditions[*]:

$$(2.12) \qquad \int_{a_j}^{b_j} w_i'(z)dz = \begin{cases} +1, & \text{for } j = i, \\ -1, & \text{for } j = i+1, \\ 0, & \text{for } j \neq i,\ j \neq i+1 \end{cases} \qquad .$$

(It is shown in reference [1] that of the m conditions (2.12) only m-1 are independent.) Now employing the alternative definition of p_{ik} and taking for C_k the doubly-counted k'th interval, one easily obtains from (2.11) the result

$$(2.13) \qquad p_{ik} = \pm 2 \int_{b_k}^{a_{k+1}} \frac{P_i(\xi)d\xi}{\sqrt{\displaystyle\prod_{j=1}^{m}(\xi-a_j)(\xi-b_j)}} \,,$$

where the ambiguity in sign is most easily resolved with the aid of (2.2c) and (2.2d).

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[*] It must be remembered that the denominator of $w_i'(z)$ changes sign on successive intervals (a_j, b_j).

Insofar as numerical computations are concerned, it would appear that formulas (2.9) and (2.13) are especially suitable. While (2.13) has an advantage over (2.9) in that integration is necessary only over a single interval, it involves the solution of the system (2.12) for the coefficients of the polynomial $P_i(z)$ and this may become laborious for large values of m. In this case it might prove preferable to employ (2.9), obtaining the function $f_i(x)$ to the desired degree of approximation by the method given in [2], § 6.

3. Extension to More General Regions

Since the coefficients of capacitance are conformal invariants, they may be determined by the method described above for any domain which can be mapped conformally onto a slit-domain. A simple example of such a domain is the entire (x,y)-plane slit along a finite number of arcs of a circle (cf. [1], § 92). By a suitable linear transformation we can map the circumference of this circle onto the x-axis, thus obtaining a slit-domain.

Another domain to which this method applies is a domain bounded externally by one circle and internally by two others. By a suitable linear transformation such a region may always be mapped into a domain with the center of all three circles collinear (cf. Fig. 2).
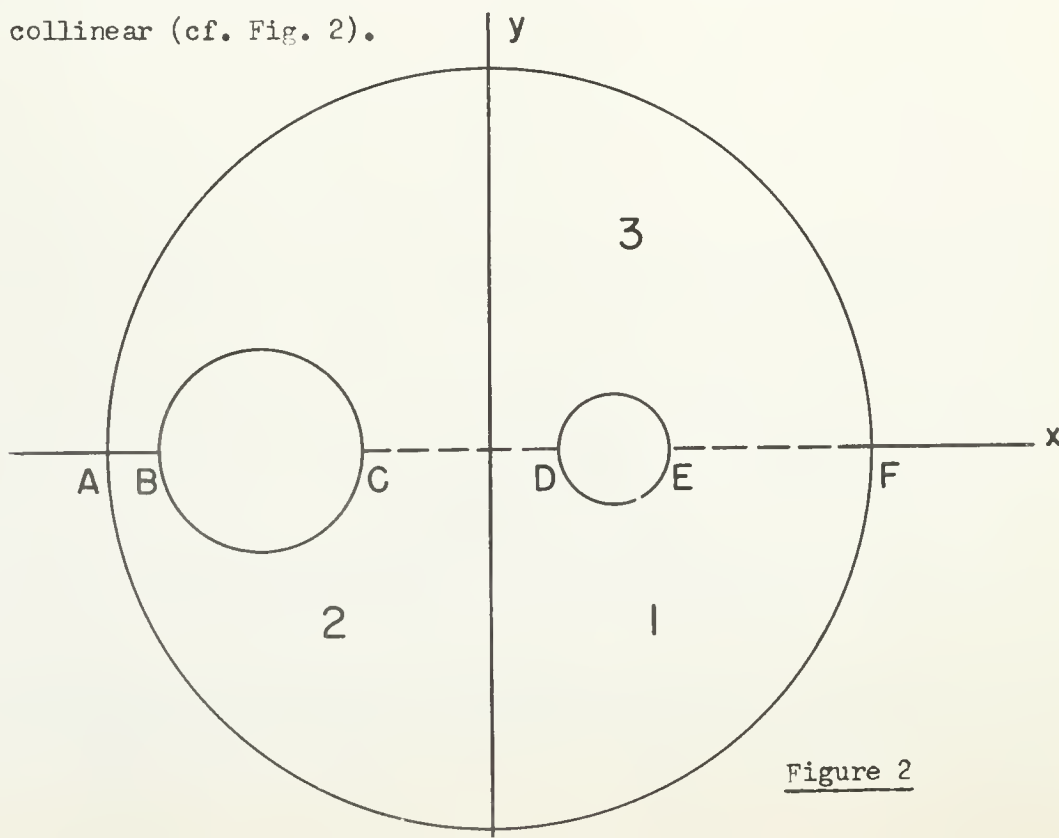

Figure 2

Now suppose that the upper half of this domain, which is simply-connected, is mapped conformally by an analytic function $\zeta = f(z)$ upon the upper half of the ζ-plane. Then the upper halves of the three circles are mapped into segments of the real axis of the ζ-plane, and the three segments of the axis of symmetry (AB, CD, EF) are mapped into the remainder of the real axis. By the Schwarz reflection principle, the entire domain of Fig. 2 is then conformally mapped onto the ζ-plane with three slits along the real axis, i.e., upon a slit-domain. A particular case of practical interest is the 'bi-filar shielded conductor'. This case will be discussed in some detail in Section 4.

Closely related to the configuration of Fig. 2 is that of the plane with any finite number of circular apertures whose centers all lie on one line (cf.Fig.3). Each half of this region is simply-connected. If, as before, we can make
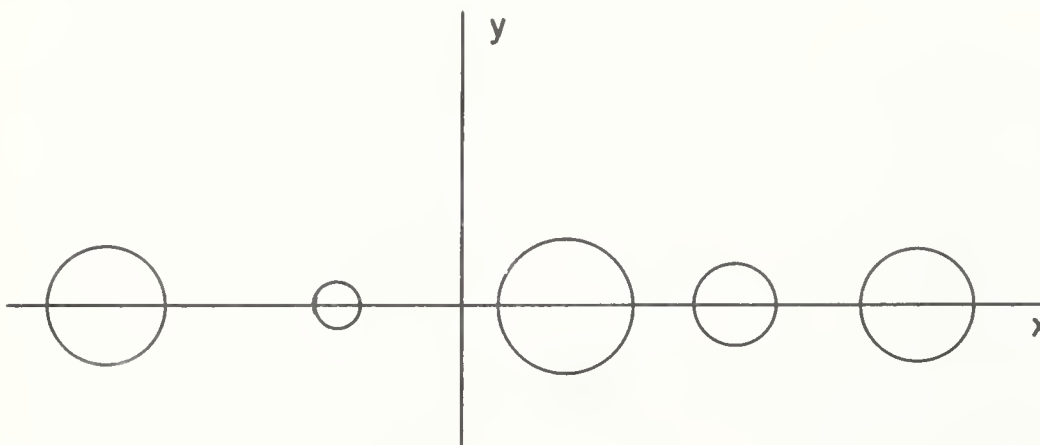

Figure 3

a conformal mapping of the upper half of this region upon the upper half of the ζ-plane, then, as in the previous case, the reflection principle immediately gives the mapping of the entire configuration upon the w-plane with collinear slits.

The use of the Schwarz reflection principle to transform a region into one bounded by collinear slits may prove of use in studying the electrostatic field created by an electrified grid.

4. An Illustrative Example

In the case of the domains described in Section 3 it has been shown that the problem of determining the coefficients p_{ik} may be reduced essentially to the problem of finding a mapping function for a simply-connected domain, regardless of the connectivity of the original domain. Since the simply-connected domain in question is bounded by parts of circles and straight lines, the required mapping can be obtained, in principle, by solving a certain non-linear third-order differential equation which is closely related to a certain linear second order equation (cf. [3], pp. 198-208). However, in practice this fact is of little use, for these differential equations contain the so-called accessory parameters of the domain, which cannot readily be determined except in the most elementary cases. But for regions of the type under consideration, it might be possible to overcome this difficulty with the help of some of the many approximate conformal mapping techniques that have been developed.

Here, by way of an example, we shall consider a case of the 'bi-filar shielded cable' which can be treated by elementary methods.
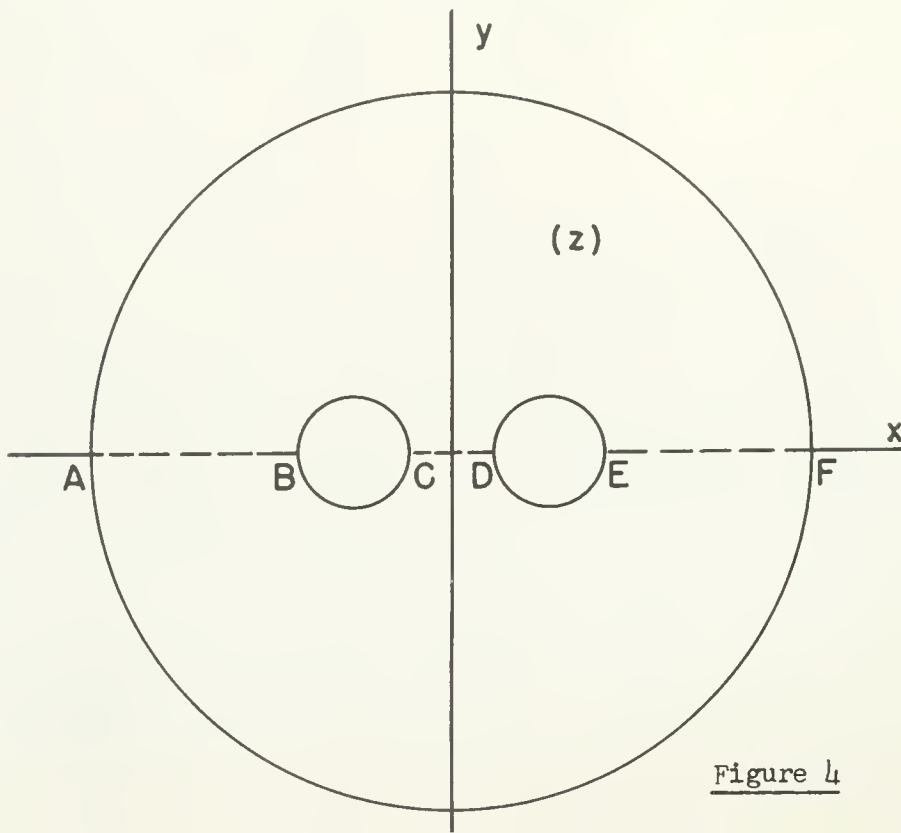

Figure 4

Referring to Fig. 4, let the radius of the outer circle be taken equal to unity (this assumption does not reduce the generality), and let the points B, C, D, E correspond to $z = -\beta, -\alpha, \alpha, \beta$ respectively. By the mapping function

$$(4.1) \qquad \zeta = \sqrt{\alpha\beta} \; \left(z + \frac{1}{z}\right)$$

the interior of the outer circle is mapped upon the exterior of the slit $-2\sqrt{\alpha\beta} \leq \zeta \leq 2\sqrt{\alpha\beta}$, and hence the domain bounded by the three circles is mapped onto the ζ-plane minus the aforementioned slit and the images of the two interior circles. In particular, if $\beta \ll 1$, so that the inner circles are small and located close to the center of the outer circle, then the mapping (4.1) may be approximated in the neighborhood of the inner circles by the linear mapping

$$(4.2) \qquad \zeta = \frac{\sqrt{\alpha\beta}}{z} \quad,$$

which transforms the inner circles into circles which meet the real axis at $\pm\sqrt{\frac{\alpha}{\beta}}$ and $\pm\sqrt{\frac{\beta}{\alpha}}$. Hence the domain of Fig. 4 is mapped by (4.1) approximately into the region indicated in Fig. 5.
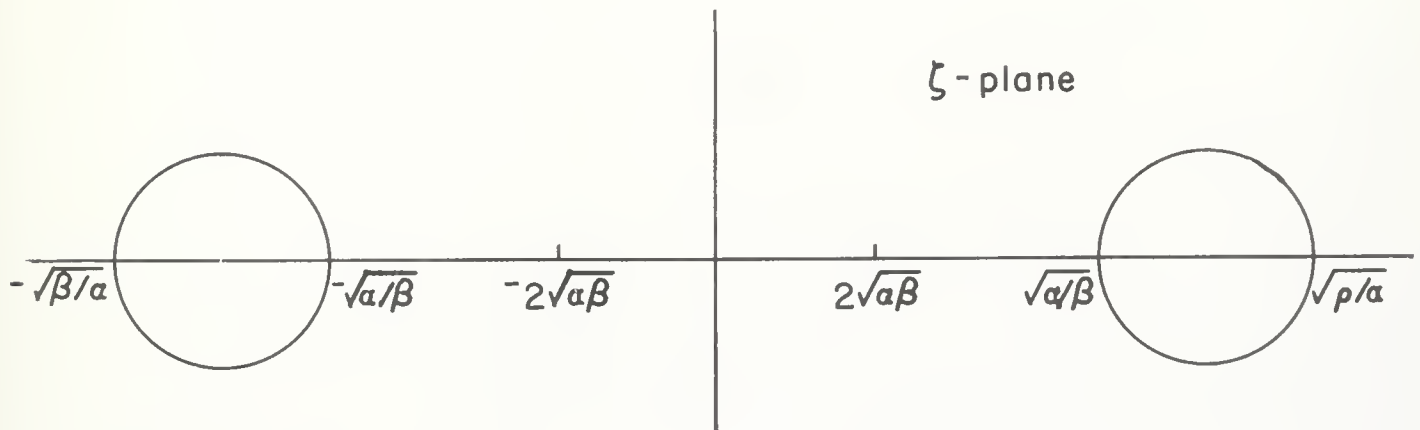

Figure 5

The centers of the circles in Fig. 5 are given by $\zeta = \pm a$, where $a = \dfrac{\alpha+\beta}{2\sqrt{\alpha\beta}}$,

and the, radius of each circle is given by $r = \dfrac{\beta-\alpha}{2\sqrt{\alpha\beta}}$. Since $a^2-r^2 = 1$,

the exterior of these two circles may be mapped upon the exterior of two

slits of the real axis by the function (cf. [3], p.297, example 9)

$$(4.3) \qquad w = \frac{1 + f(\frac{1+\zeta}{1-\zeta},\rho)}{1 - f(\frac{1+\zeta}{1-\zeta},\rho)} \quad ,$$

where

$$\rho = \frac{\sqrt{\beta}-\sqrt{\alpha}}{\sqrt{\beta}+\sqrt{\alpha}}$$

and

$$(4.4) \quad f(t,\rho) = \frac{\rho^2}{t} \; \frac{\displaystyle\prod_{n=0}^{\infty}(1 + \rho^{8n-2}t^2)\prod_{n=1}^{\infty}(1 + \rho^{8n+2}t^{-2})}{\displaystyle\prod_{n=0}^{\infty}(1 + \rho^{8n+2}t^2)\prod_{n=0}^{\infty}(1 + \rho^{8n+6}t^{-2})}$$

(cf. [3], Chapt. VI, Sec. 3, equations (32) and (49)). The circles map onto

the twice-counted slits

$$- \frac{1+L(\rho)}{1-L(\rho)} \le w \le - \frac{1-L(\rho)}{1+L(\rho)}$$

and

$$\frac{1-L(\rho)}{1+L(\rho)} \le w \le \frac{1+L(\rho)}{1-L(\rho)}$$

respectively, where

$$(4.5) \qquad L(\rho) = 2\rho \prod_{n=1}^{\infty}(\frac{1+\rho^{8n}}{1+\rho^{8n-4}})^2 .$$

The interval $-2\sqrt{\alpha\beta} \le \zeta \le 2\sqrt{\alpha\beta}$ maps onto the infinite interval

$$|w| \ge \frac{1-f(\dfrac{1+2\sqrt{\alpha\beta}}{1-2\sqrt{\alpha\beta}},\rho)}{1+f(\dfrac{1+2\sqrt{\alpha\beta}}{1-2\sqrt{\alpha\beta}},\rho)}$$

of the real axis. Thus the domain of Fig. 4 has been approximately mapped

into a slit-domain, and the formulas given there may be employed to determine

the p_{ik}.

To give a numerical illustration, let $\alpha = \frac{1}{20}$, $\beta = \frac{1}{5}$. Then $\rho = \frac{1}{3}$, and, since the infinity products (4.4) and (4.5) converge rapidly, one obtains very easily

(4.6) $\frac{1-L(\rho)}{1+L(\rho)} = 0.212$, $\quad \frac{1+L(\rho)}{1-L(\rho)} = 4.726$, $\quad \dfrac{1-f(\frac{1+2\sqrt{\alpha\beta}}{1-2\sqrt{\alpha\beta}},\rho)}{1+f(\frac{1+2\sqrt{\alpha\beta}}{1-2\sqrt{\alpha\beta}},\rho)} = 8.628$.

In order to work with more convenient numbers, we employ the transformation

(4.7) $\qquad\qquad \tilde{z} = \frac{.2}{.212}\ z,$

thus obtaining in the $\tilde{z}$-plane a slit-domain characterized by the following numbers (cf. Fig. 1):

(4.8) $\quad a_1 = -8.1,\quad b_1 = -4.5,\quad a_2 = -0.2,\quad b_2 = 0.2,\quad a_3 = 4.5,\quad b_3 = 8.1.$

On account of the low connectivity of the domain (m=3) it was decided to employ formula (2.13) to evaluate the p_{ik}. The coefficients p_{22} and p_{21} (the numbering of the boundary components is given in Fig. 4 and Fig. 5, and is in accordance with the numbering given proceding Fig. 1) were determined as follows: The polynomial $P_2(z)$, which according to the discussion of §2 is of first degree, was replaced in (2.12) by the quadratic polynomial az^2+bz+c with unknown coefficients a, b, c. The integrals appearing in (2.12) were computed by interpolation (the Tchebyshev five-point formula was used) and the resulting system of linear equations was solved for the coefficients a, b, c, with the following results:

(4.9) $\quad a = -9.3 \times 10^{-8},\quad b = -1.962,\quad c = -11.608.$

(The radical appearing in (2.12) was taken positive on the first and third intervals and negative on the second interval.) The extremely small value obtained for a, whose exact value must be zero, serves as an excellent check on the accuracy of the computations. The expression for $P_2(z)$ thus obtained

was then employed in (2.13), with the following results:

(4.10) $p_{21} = -2.153$, $p_{22} = +3.820$.

By symmetry, $p_{11} = p_{22}$, and now the remaining six coefficients are obtained with the aid of (2.2a) and (2.2b). Thus, the following table of values of the p_{ik} was obtained.

k \ i	1	2	3
1	+3.820	-2.153	-1.667
2	-2.153	+3.820	-1.667
3	-1.667	-1.667	+3.334

As a check, p_{22} was also computed by means of (2.5) and (2.10), and excellent agreement was obtained.

Acknowledgment

We wish to thank Mr. Charles Kahane, who so capably carried out the computations connected with the illustrative example of Section 4.

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